

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property
Organization
International Bureau



(43) International Publication Date
3 February 2005 (03.02.2005)

PCT

(10) International Publication Number
WO 2005/009814 A1

(51) International Patent Classification⁷: B60T 8/00,
7/12, B60L 15/20

(21) International Application Number: PCT/JP2004/011005

(22) International Filing Date: 26 July 2004 (26.07.2004)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
2003-203011 29 July 2003 (29.07.2003) JP

(71) Applicant (for all designated States except US): TOYOTA JIDOSHA KABUSHIKI KAISHA [JP/JP]; 1, Toyota-cho, Toyota-shi, Aichi, 4718571 (JP).

(72) Inventor; and

(75) Inventor/Applicant (for US only): HOMMI, Akira

[JP/JP]; c/o TOYOTA JIDOSHA KABUSHIKI KAISHA,
1, Toyota-cho, Toyota-shi, Aichi, 4718571 (JP).

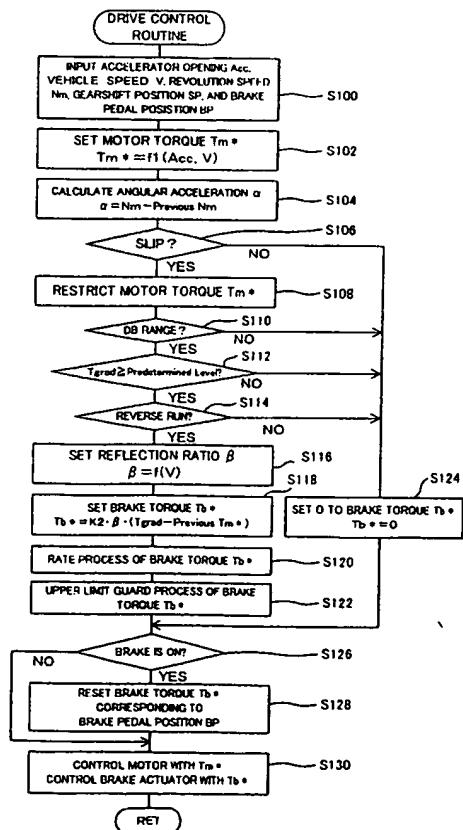
(74) Agent: ITEC INTERNATIONAL PATENT FIRM;
Pola-Nagoya Bldg. 9-26, Sakae 2-chome, Naka-ku,
Nagoya-shi, Aichi, 4600008 (JP).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM),

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(54) Title: VEHICLE AND CONTROL METHOD OF VEHICLE SLIP-DOWN VELOCITY



(57) Abstract: In response to detection of a slip-down of a vehicle under restriction of a motor torque Tm^* , which is required for a drive shaft linked with drive wheels, due to the occurrence of a slip caused by spin of the drive wheels on an ascending slope, the technique of the invention multiplies torque insufficiency by a ratio (reflection ratio β) specified according to a vehicle speed V in a reverse direction, so as to set a brake torque Tb^* . The torque insufficiency corresponds to a difference between the restricted motor torque Tm^* and a balancing torque $Tgrad$ corresponding to a road surface gradient set according to the relation between an acceleration of the vehicle and a torque output to the drive shaft. The setting of the brake torque Tb^* makes the velocity of the slip-down of the vehicle approach to a preset vehicle speed. The brake torque Tb^* is applied by hydraulic brakes attached to driven wheels, which are different from the drive wheels. The arrangement of the invention regulates the velocity of the vehicle that slips down the ascending slope by the restriction of the motor torque Tm^* .

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— before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments

Published:

— with international search report

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